

## §14. Dynamical zeta function

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We continue working with a

Convex co-compact hyperbolic surface

$M = \Gamma \backslash \mathbb{H}^2$  where  $\Gamma \subset PSL(2, \mathbb{R})$  is  
a Schottky group.

### §14.1. Selberg zeta function

Let  $\varphi^t: SM \rightarrow SM$  be the geodesic flow.

A closed geodesic on  $M$

Corresponds to a pair  $((x, v), T)$   
where  $(x, v) \in SM$ ,  $T > 0$ , and

$$\varphi^T(x, v) = (x, v).$$

We identify  $((x, v), T)$  with

$$(\varphi^t(x, v), T) \quad \forall t \in \mathbb{R}.$$

Note that we necessarily have

$$(x, v) \in K \leftarrow \text{trapped set}.$$

We say  $((x, v), T)$  is a primitive closed geodesic, if

$$\varphi^t(x, v) \neq (x, v) \text{ for all } t \in (0, T).$$

One can show that  $\exists C \in \mathbb{R}$

the number of closed geodesics of period  $\leq R$  is  $O(e^{CR})$ .

(This can be proved using the Stable / Unstable manifold Theorem)

for the geodesic flow on  $K$

Similarly to Pset 4, Exercise 3).

Defn. For  $s \in \mathbb{C}$ ,  $\operatorname{Re} s > C$ ,

define the Selberg zeta function

$$Z_M(s) = \prod_T \prod_{k=0}^{\infty} (1 - e^{-(s+k)T})$$

where  $\prod_T$  is over the periods of primitive closed geodesics, with multiplicity.

For  $\operatorname{Re} s > c$ , the product

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Converges since

$$\sum_T \sum_{k=0}^{\infty} |e^{-(s+k)T}| < \infty :$$

Split into pieces (assume for simplicity  $T \geq 1$  always)

$$r \leq T < r+1, \quad r \in \mathbb{N},$$

at most  $O(e^{Cr})$  terms  $T$   
in each piece, so get a bound by

$$\begin{aligned} & \sum_{r=1}^{\infty} \sum_{k=0}^{\infty} e^{Cr} |e^{-(s+k)r}| \\ &= \sum_{r=1}^{\infty} \sum_{k=0}^{\infty} e^{(c - \operatorname{Re} s - k)r} = \quad (\text{geometric progression}) \\ &= \sum_{k=0}^{\infty} \frac{e^{c - \operatorname{Re} s - k}}{1 - e^{c - \operatorname{Re} s - k}} < \infty. \end{aligned}$$

Note:  $\sum_M(s)$  is holomorphic  
in  $s$  when  $\operatorname{Re} s > c$ .

In this lecture we show that

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$Z_M(s)$  extends to an entire function of  $s \in \mathbb{C}$ .

We will do this using transfer operators and Fredholm determinants.

Example: hyperbolic cylinder

$$\mathbb{R}_r \times (\mathbb{R}/\ell\mathbb{Z})_\theta, \quad g = dr^2 + \cosh^2 r d\theta^2$$

2 primitive closed geodesics of length  $\ell$  because direction matters:



$$Z_M(s) = \prod_{k=0}^{\infty} \left(1 - e^{-(s+k)\ell}\right)^2$$

From here we see that  $Z_M(s)$  is entire and its zeros are when  $e^{-(s+k)\ell} = 1$ , i.e.

$$s = \frac{2\pi i}{\ell} p - k, \quad p \in \mathbb{Z}, \quad k \in \mathbb{N}.$$

# Relation of closed geodesics

To words in  $\Gamma$ :

Assume that  $(x, v) \in SM$

gives a closed geodesic of period  $T > 0$ ,

i.e.  $\boxed{\varphi^T(x, v) = (x, v)}.$

Let us lift it: if

$\tilde{\pi}: SH^2 \rightarrow SM$  is the projection map

then choose  $(y, w) \in SH^2$  such that

$$\boxed{\tilde{\pi}(y, w) = (x, v)}$$

Denoting by  $\varphi_t$  the geodesic flows on

$SM$  and on  $SH^2$ , we then have

$$\tilde{\pi}(\varphi^T(y, w)) = \varphi^T(x, v) = (x, v) = \tilde{\pi}(y, w).$$

$\downarrow$

Thus  $\exists \gamma \in \Gamma \setminus \{I\}$

such that (with the standard action  
of  $\gamma$  on  $SU(2)$ )

$$\varphi^T(y, w) = \gamma \cdot (y, w).$$

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Example: hyperbolic cylinder

Say for simplicity that  $\Gamma$  is generated

by  $\gamma_1 = \begin{pmatrix} e^{l/2} & 0 \\ 0 & e^{-l/2} \end{pmatrix}$ ,  $\gamma_1 \cdot z = e^l \cdot z$

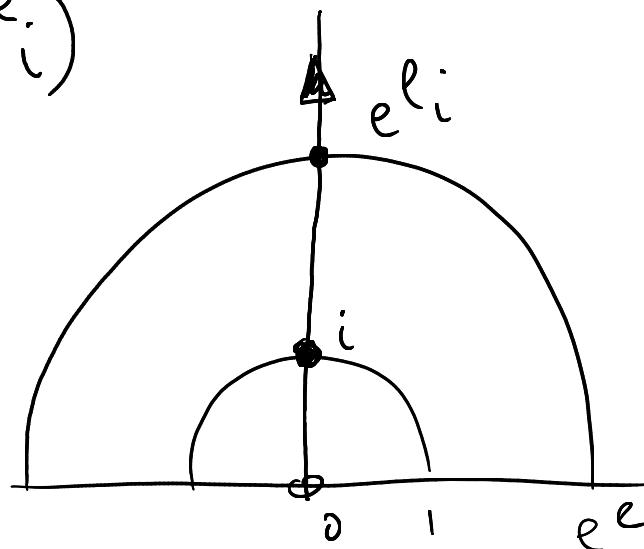
$$\gamma_1 \cdot (y, w) = (e^l y, e^l w).$$

Then we take  $T = l$ ,  $\gamma = \gamma_1$ ,

$$(y, w) = (i, i)$$

$$\varphi^T(y, w) = (e^l i, e^l i)$$

$$= \gamma_1 \cdot (y, w).$$



Coming back to the general case:

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$(y, w) \in SH^2$ ,  $\gamma \in \Gamma \setminus \{\text{I}\}$ ,  $T > 0$ ,

$$\varphi^T(y, w) = \gamma \cdot (y, w)$$

This describes all closed geodesics on  $M$  up to the following transformations which would give the same geodesic:

- $(y, w) \mapsto \varphi^s(y, w)$ ,  $T$  same  
(then  $\tilde{\pi}(\varphi^s(y, w)) = \varphi^s(\tilde{\pi}(y, w))$   
is a different point on the same closed geodesic)
  - $(y, w) \mapsto \tilde{\gamma} \cdot (y, w)$  for some  $\tilde{\gamma} \in \Gamma$   
(taking a different preimage in  $SH^2$   
of the same point  $(x, v) \in SM$ )
- and  $\tilde{\gamma} \mapsto \tilde{\gamma} \cdot \tilde{\gamma} \cdot \tilde{\gamma}^{-1}$

Now, since  $\gamma \in P \setminus \{I\}$

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We can write

$\gamma = \gamma_{\vec{a}}$  for some  $\vec{a} = a_1 \dots a_n \in W$ .

Recall that  $\gamma$  here is defined up to conjugation by an element of  $P$ .

Then we can choose  $\gamma_{\vec{a}}$

so that  $a_1 \neq \bar{a}_n$ .

Indeed, if  $a_1 = \bar{a}_n$ , then

$$\gamma = \gamma_{a_1} \gamma_{a_2} \dots a_{n-1} \gamma_{a_n} = \gamma_{a_1} \gamma_{a_2} \dots a_{n-1} \gamma_{a_1}^{-1}$$

is conjugate to  $\gamma_{a_2 \dots a_{n-1}}$

and we can repeat the process...

The element  $\gamma_{\vec{a}}$  is hyperbolic:

$$\gamma_{\vec{a}} (\mathcal{D}_{a_1}) \subset \mathcal{D}_{a_1}, \quad \gamma_{\vec{a}}^{-1} (\mathcal{D}_{\bar{a}_n}^-) \subset \mathcal{D}_{\bar{a}_n}^-$$

So  $\gamma_{\vec{a}}$  has an attractive / repulsive fixed pt  
 $\gamma_{+, \vec{a}} \in \mathcal{D}_{a_1}, \quad \gamma_{-, \vec{a}} \in \mathcal{D}_{\bar{a}_n}$ .

In fact,  $\forall j \geq 0$

$$\gamma_{+, \vec{a}} \in \mathcal{X}_{\vec{a}}^j (\mathbb{D}_{a_1})$$

$$= \mathbb{D}_{\underbrace{\vec{a} \vec{a} \dots \vec{a}}_{\text{concatenated } j \text{ times}}, a_1}$$

$$\text{so } \gamma_{+, \vec{a}} \in \Lambda_\Gamma.$$

$$\text{Similarly } \gamma_{-, \vec{a}} \in \Lambda_\Gamma.$$

$$\text{And } q^T(y, w) = \mathcal{X}_{\vec{a}} \cdot (y, w)$$

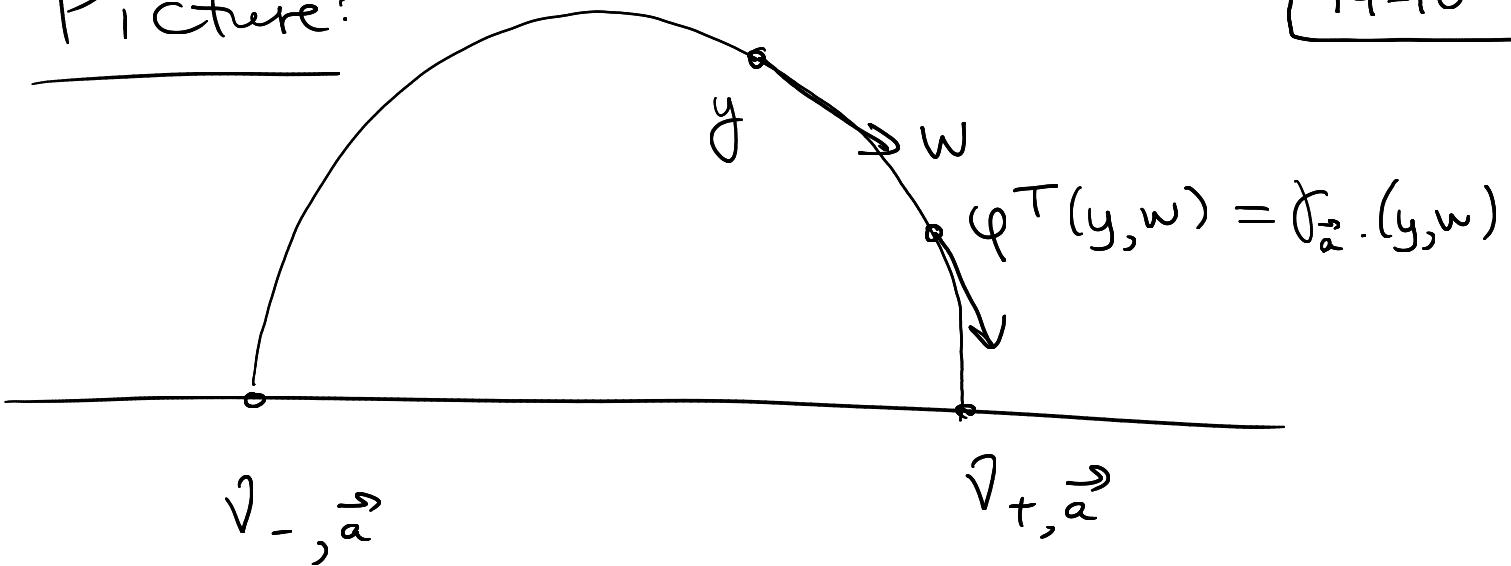
$(y, w)$  lies on the geodesic

from  $\gamma_{-, \vec{a}}$  to  $\gamma_{+, \vec{a}}$

$$\text{and } e^T = \mathcal{X}'_{\vec{a}} (\gamma_{-, \vec{a}})$$

Indeed, we can conjugate  $\mathcal{X}_{\vec{a}}$  to  $\begin{pmatrix} e^{i/2} & 0 \\ 0 & e^{-i/2} \end{pmatrix}$   
 in which case this is straightforward to check,  
 with the repulsive fixed point  $\gamma_{-, \vec{a}} \sim 0$   
 and  $\partial_z (e^z z)|_{z=0} = e^l$ .

Picture:



Thus we see that

closed geodesics on  $M = \Gamma \backslash H^2$

are bijective to

closed words

$$\vec{a} = a_1 \dots a_n \in W^n, \quad a_n \neq \bar{a}_1$$

modulo conjugation of the corresponding  $\vec{\gamma}_{\vec{a}}$   
(in  $\Gamma$ )

We can check that

2 closed words give conjugate  $\vec{\gamma}_{\vec{a}}$   
iff they are cyclic permutations of each other  
e.g.  $\vec{\gamma}_{a_1 \dots a_n}$  conjugate to  $\vec{\gamma}_{a_2 \dots a_n a_1}$ .

Finally, a closed geodesic is primitive iff the corresponding word is primitive i.e. it's not a power of another word.

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More precisely / to recap:

Defn. A closed word is

$a_1 \dots a_n$  s.t.  $a_1, \dots, a_n \in A$  and  
 $\bar{a}_1 \neq a_2, \bar{a}_2 \neq a_3, \dots, \bar{a}_{n-1} \neq a_n, \bar{a}_n \neq a_1$ .

- A closed word  $\vec{a} = a_1 \dots a_n$  is primitive, if there exists no  $l < n$  s.t.  $a_{j+l \pmod{n}} = a_j \quad \forall j$   
 (i.e. not a power of a shorter word)  
 (e.g. 121 primitive, 1212 not primitive)
- Two closed words  $a_1 \dots a_n, b_1 \dots b_n$  are equivalent if  $\exists l \quad \forall j$   
 $a_j = b_{(j+l) \pmod{n}}$  (e.g. 123 ~ 312 ~ 231  
 but 123 ≠ 132)

Then we have

Thm The set of primitive (oriented)  
closed geodesics on  $M = \Gamma \backslash H^2$   
is in one-to-one correspondence  
with the set of equivalence classes  
of primitive closed words  $\gamma_{\vec{a}}$   
in the group  $\Gamma$ .

Here the length  $l$  of a geodesic  
is related to  $\vec{a}$  by the formula

$$e^l = \gamma'_{\vec{a}} (\gamma_{-, \vec{a}})$$

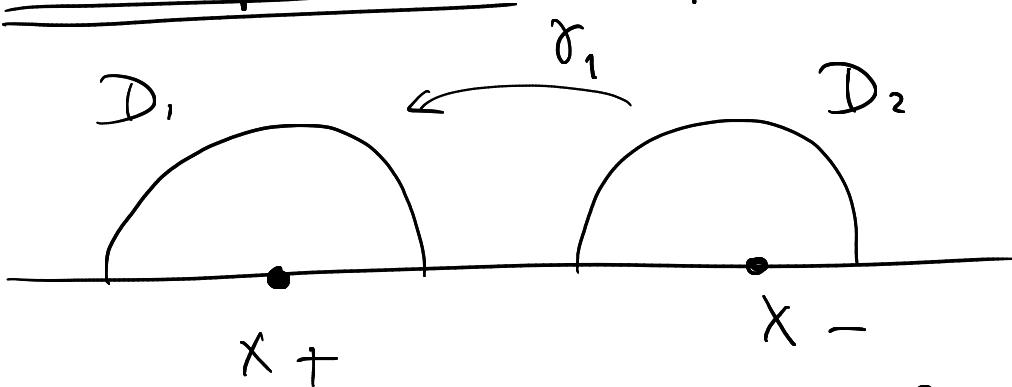
where  $\gamma_{-, \vec{a}}$  is the repulsive  
fixed point of  $\gamma_{\vec{a}}$ .



Example 1: hyperbolic cylinder

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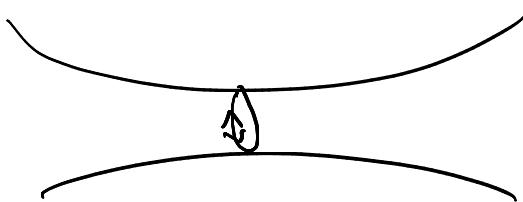
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$x \pm$  fixed points of  $\sigma_1$

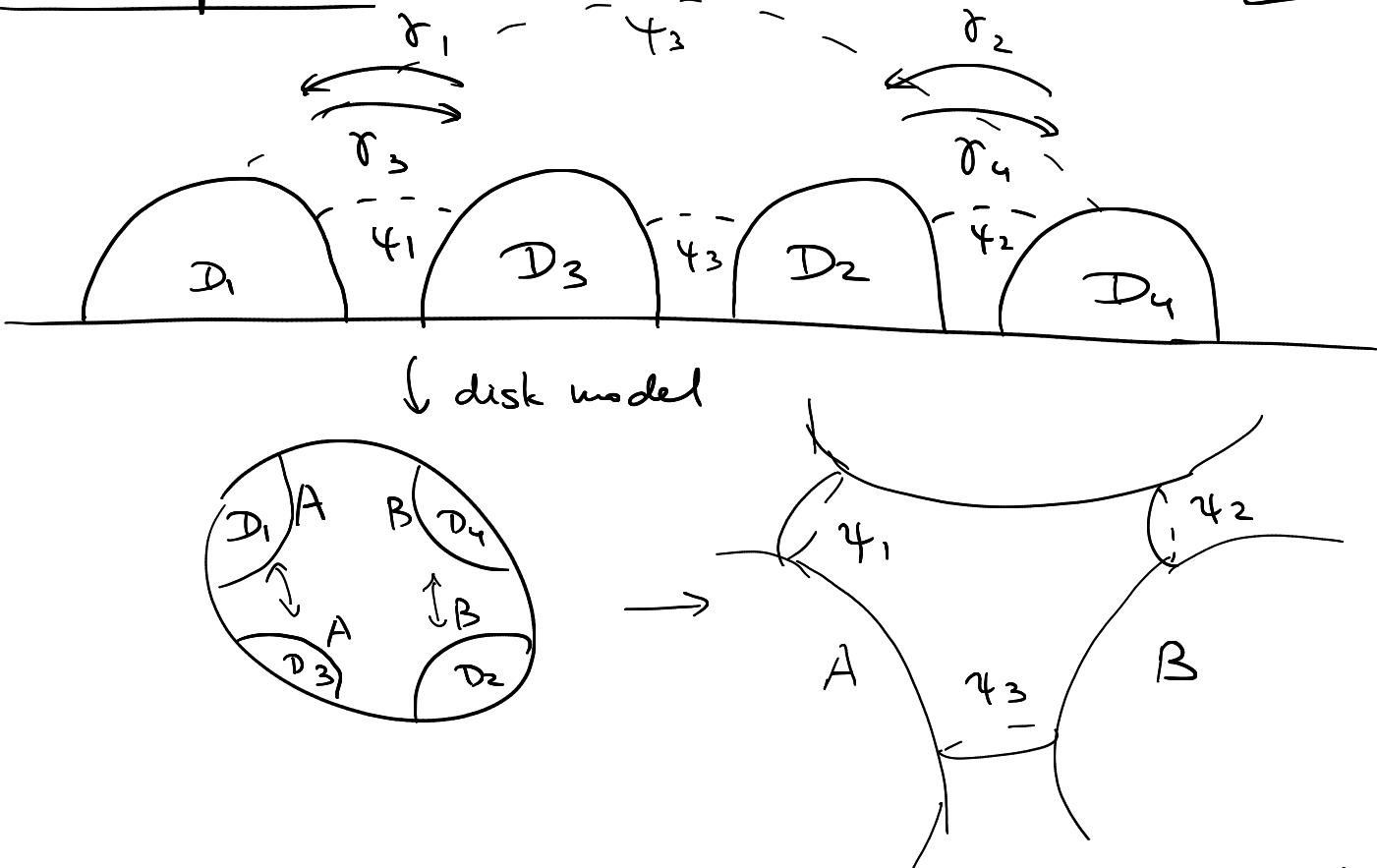
There are 2 primitive closed words:

1 and 2. These correspond  
to the 2 primitive closed  
geodesics on  $M$ :



## Example 2: 3-funnel surface

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One can check that the closed geodesics  $\gamma_1, \gamma_2, \gamma_3$  correspond to the words (for a specific choice of orientation on  $\gamma_j$ )

$$\gamma_1 \sim 1$$

$$\gamma_2 \sim 2$$

$$\gamma_3 \sim 12$$

Rank. This all agrees with geometrical considerations:  $\Gamma = \text{fundamental group}$  and curvature  $< 0 \Rightarrow$  exactly 1 closed geodesic in each free homotopy class =  $\Gamma / \text{Conjugation}$

## §14.2. Determinants of transfer operators

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Recall the transfer operator

$$\mathcal{L}_S : C^0(\Lambda_\Gamma) \hookrightarrow ,$$

$$\mathcal{L}_S f(x) = \sum_{\substack{a \in \Lambda \\ a \neq b}} f(\gamma_a(x)) \gamma'_a(x), \quad x \in \Lambda_\Gamma \cap D_b$$

We now define it on a different

Space:

Denote  $D = \bigsqcup_{a \in \Lambda} D_a$  (union of the original Schottky disks)

here  $D \subset \mathbb{C}$ .

Define  $\mathcal{H}(D) = \{f \in L^2(D) : f \text{ is holomorphic on } D^\circ\}$   
wrt Lebesgue measure on  $\mathbb{C}$

One can show that

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$\mathcal{H}(\mathbb{D}) \subset L^2(\mathbb{D})$  is

a closed subspace w.r.t.  $L^2$  norm

and thus  $\mathcal{H}(\mathbb{D})$  is a  
Hilbert Space.

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Trace class operators (a very brief intro)

If  $\mathcal{H}$  is a Hilbert Space,

We say that a compact operator

$A: \mathcal{H} \rightarrow \mathcal{H}$  is trace class, if

$$\sum_j \sigma_j(A) < \infty \text{ where } \sigma_1(A), \sigma_2(A) \dots$$

Are the singular values of  $A$ :

$$\text{Spectrum}(A^* A) = \{\sigma_j(A)^2\}$$

$\mathcal{L}_*(\mathcal{H}) :=$  Space of all trace class operators

The expression

$$\|A\|_{\text{Tr}} = \sum_j \sigma_j(A)$$

defines a norm, called the trace norm.

Properties:

- $(\mathcal{L}(\mathcal{H}), \|\cdot\|_{\text{Tr}})$  is a Banach Space and finite rank operators are dense in it
- Ideal property: if  $A \in \mathcal{L}(\mathcal{H})$  and  $B: \mathcal{H} \rightarrow \mathcal{S}$  is bounded then  $AB, BA \in \mathcal{L}(\mathcal{H})$  and  $\|AB\|_{\text{Tr}}, \|BA\|_{\text{Tr}} \leq \|A\|_{\text{Tr}} \cdot \|B\|_{\mathcal{H} \rightarrow \mathcal{S}}$

- If  $A \in \mathcal{L}_1(\mathcal{H})$ , we can define its trace

$\text{tr } A \in \mathbb{C}$  :

$\text{tr } A$  defined the usual way  
on finite rank  $A$  &  
continuous w.r.t.  $\|\cdot\|_{\text{Tr}}$

- If  $A \in \mathcal{L}_1(\mathcal{H})$ , we can define the determinant

$\det(I+A) \in \mathbb{C}$   
which is the usual  $\det$  when  $A$  has  
finite rank & continuous w.r.t.  $\|\cdot\|_{\text{Tr}}$

- $\det(I+A) = 0 \iff$   
 $\iff I+A$  is not invertible  
 $\mathcal{H} \rightarrow \mathcal{H}$

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Coming back to  $L_s$ ,

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for  $s \in \mathbb{C}$  define

$L_s : \mathcal{H}(\mathbb{D}) \rightarrow \mathcal{H}(\mathbb{D})$  by

$$L_s f(z) = \sum_{\substack{a \in A \\ a \neq b}} f(\gamma_a(z)) [\gamma'_a(z)]^s, \quad z \in \mathbb{D}_b.$$

Here  $[\gamma'_a(z)]^s = \exp(s \log \gamma'_a(z))$

and  $\log \gamma'_a(z)$  is well-defined

by requiring  $\log \gamma'_a(x) \in \mathbb{R}$

when  $x \in I_b = \mathbb{D}_b \cap \mathbb{R}$ .

This works since for  $a \neq b$  we

have  $\gamma_a(\mathbb{D}_b) = \mathbb{D}_{ab} \subset \mathbb{D}_a$ .

Now we can present

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Thm The operator  $\mathcal{L}_s$   
is trace class on  $\mathcal{H}(\mathbb{D})$   
for all  $s \in \mathbb{C}$  and for  $\text{Re } s > 1$   
we have  $Z_M(s) = \det(I - \mathcal{L}_s)$

Selberg zeta function

This gives the holomorphic extension  
of  $Z_M$  to  $\mathbb{C}$ , since

$\det(I - \mathcal{L}_s)$  is holomorphic  
in  $s \in \mathbb{C}$ .

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We will not give the proof, see  
Borthwick, Thm 15.10.

But here are a few ingredients:

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① If  $\Omega \subset \mathbb{C}$  is open and

$\gamma: \Omega \rightarrow \Omega$  is a holomorphic map

such that  $\boxed{\gamma(\Omega) \subset K}$  for some  
compact  $K \subset \Omega$ , and we define

the operator  $\gamma^*: \mathcal{H}(\Omega) \rightarrow \mathcal{H}(\Omega)$ ,

$$\gamma^* f(z) = f(\gamma(z)),$$

$\mathcal{H}(\Omega) = \{f \in L^2(\Omega; \text{Lebesgue}) :$

$f$  is holomorphic on  $\Omega\}$

then  $\gamma^*: \mathcal{H}(\Omega) \hookrightarrow$

is trace class.

Moreover, if  $\gamma$  has a unique  
fixed point  $z_0 \in \Omega$ , with  $\gamma'(z_0) \neq 1$ ,

then 
$$\boxed{\text{tr } \gamma^* = \frac{1}{1 - \gamma'(z_0)}}$$

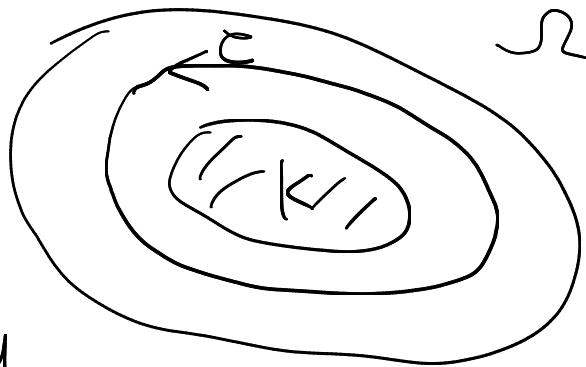
(Lefschetz fixed point formula)

# Proof (sketch)

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Take a contour  $\gamma \subset \Omega$

enclosing  $K$ :



Then  $\forall z \in \Omega$ ,

$\gamma(z) \in K$ , so by the Cauchy Integral Formula we have

$$\gamma^* f(z) = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(w)}{w - \gamma(z)} dw.$$

$$\text{That is, } \gamma^* = \frac{1}{2\pi i} \oint_{\gamma} A_w dw$$

as operators on  $\mathcal{H}(\Omega)$ , where

$$A_w : \mathcal{H}(\Omega) \hookrightarrow,$$

$$A_w f(z) = \frac{f(w)}{w - \gamma(z)}, \quad z \in \Omega, w \in \gamma.$$

$A_w$  is rank 1 and thus trace class  
and the  $\int_{\gamma}$  converges in trace class norm.  
So  $\gamma^*$  is trace class.

To compute the trace, note that

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$$\forall w \in \mathcal{C}, A_w = u_w \otimes v_w$$

in the sense that  $A_w f = u_w(f) \cdot v_w \quad \forall f \in H(\mathbb{R})$

where  $u_w: H(\mathbb{R}) \rightarrow \mathbb{C}, v_w \in H(\mathbb{R})$

are given by

$$u_w(f) = f(w), \quad v_w(z) = \frac{1}{w - \delta(z)}.$$

$$\text{Then } \operatorname{tr} A_w = u_w(v_w) = \frac{1}{w - \delta(w)}.$$

Integrating over  $\mathcal{C}$ , we get

$$\operatorname{tr} \delta^* = \frac{1}{2\pi i} \oint \frac{dw}{w - \delta(w)}$$

and it remains to use the Residue Theorem

$$\text{to see that } \operatorname{tr} \delta^* = \frac{1}{1 - \delta'(z_0)}.$$

□



② Using ①, we can check

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that  $L_S : \mathcal{H}(D) \hookrightarrow$  is trace class

(as  $\forall a \neq b, \mathcal{X}_a(D_b) \subset D_a$ )

and compute the trace of  $L_S^k$

for any  $k \geq 1$  using the Lefschetz fixed point formula. The result

features the fixed points of

$\mathcal{X}_{\vec{a}}$  for closed words  $\vec{a} = a_1 \dots a_k$ ,

which are related to closed geodesics on  $M$  by the discussion in §14.1.

To deal with the determinant, we write

$\forall z \in \mathbb{C}$  small enough

$$\log \det(I - z L_S) = \operatorname{tr} \log(I - z L_S)$$

$$= - \operatorname{tr} \sum_{k \geq 1} \frac{(z L_S)^k}{k} \stackrel{(z \text{ small})}{=} - \sum_{k \geq 1} \frac{z^k}{k} \operatorname{tr} L_S^k$$

And for  $\operatorname{Re} s \gg 1$ , can take  $z = 1$ .  $\square$

$\uparrow$  already computed

### §14.3. More on zeta functions

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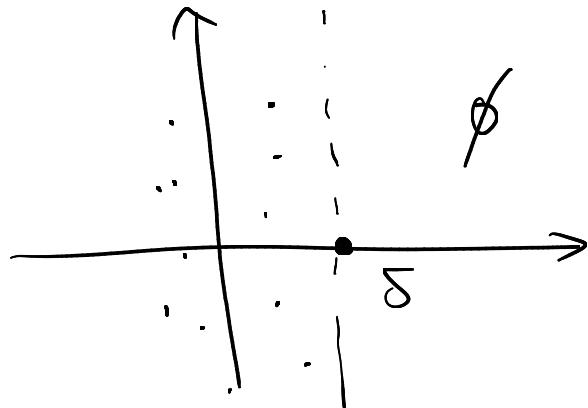
(NO PROOFS AT ALL HERE)

Let  $(M, g)$  be a convex co-compact hyperbolic surface which is not a hyperbolic cylinder.

Here are some basic facts

about the Selberg zeta function  $Z_M(s)$  (or rather, its extension to  $s \in \mathbb{C}$ ):

- $Z_M$  has a simple zero at  $s = \delta$  (note:  $Z_M(s) = \det(I - Ls)$ ,  $(I - Ls)^* \mu = \mu$  where  $\mu$  is the Patterson-Sullivan measure)
- $Z_M$  has no other zeros in  $\operatorname{Re} s \geq \delta$ .
- We call zeros of  $Z_M(s)$  the resonances of  $M$ .



Using these facts, one can show

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## Prime Geodesic Thm

Let  $N_M(R) = \{ \text{number of primitive oriented closed geodesics on } M \text{ of period } \leq R \}$ .

Then as  $R \rightarrow \infty$ ,

$$N_M(R) = \frac{e^{\delta R}}{\delta R} (1 + o(1)).$$

For the proof, see e.g.

Berthwick, Thm. 14.20.

(Note: still works if  $M$  is compact in which case  $\delta = 1$ )

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Naud 2005,  $\exists \varepsilon = \varepsilon(M) > 0$

s.t.  $N_M(R) = \text{li}(e^{\delta R}) + O(e^{(\delta-\varepsilon)R})$   
where  $\text{li}(x) = \int_2^x \frac{dt}{\log t}$ .

Bourgain-D'17: can take  $\varepsilon = \varepsilon(\delta)$  only  
(uses additive combinatorics)

What about general geodesic flows on negatively curved manifolds? 18.118  
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Thm [Giulietti - Liverani - Pollicott 2012]

Let  $\varphi^t: X \rightarrow X$  be an Anosov flow.

Then the Ruelle zeta function

$$Z_R(s) = \prod_{\ell \in \mathcal{L}} (1 - e^{-s\ell}), \quad \operatorname{Re} s > 1,$$

lengths of primitive closed orbits of  $\varphi^t$   
 admits a meromorphic continuation  
 to  $s \in \mathbb{C}$ .

First pole:  $\delta = h_{\text{top}}(\varphi^t)$

topological entropy

and a version of Prime Orbit Thm  
 holds

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D- Zworski: another proof,

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writing  $Z(s) = \det(P-s)$ "

where  $P = L_V$ , Lie derivative  
w.r.t.  $V$ ,  $\varphi^t = e^{tV}$ , on differential  
forms.

This is not trace class

but one can make sense of  
that using the Atiyah-Bott-Guillemin  
Hörmander's  
trace formulae,  
propagation of singularities, and  
Melrose's radial estimates

D-Guillarmou 2014 :

noncompact case, e.g. "convex co-compact"  
variable negative curvature manifolds  
There are also relations to topology:  
multiplicity of  $s=0$  as a singularity of  
 $Z(s)$  is related to Betti numbers...